

```

> restart; kernelopts(opaquemodules=false):
We are using the standard Maple 18 Library
> libname:="/home/me350/Programs/Maple18/lib";
      libname := "/home/me350/Programs/Maple18/lib"

```

(1)

```

We make use of the following packages:
> with(plots):
  with(RegularChains):
  with(SemiAlgebraicSetTools):

```

Additionally, we use Maple code written at the University of Bath: The ProjectionCAD package (should be hosted alongside this worksheet).

```

> read("ProjectionCAD.mpl"):
  with(ProjectionCAD):

```

"This is V3.18 of the ProjectionCAD module from 11th February 2015,
designed and tested for use in Maple 18."

(2)

Section 4 Example

```

> f1 := x-y+z^2:
  f2 := z^2-u^2+v^2-1:
  f3 := x+y+z^2:
  f4 := z^2+u^2-v^2-1:
  g := x^2-1:
  h := z:
  F := [f1,f2,f3,f4,g,h]:
  lsas := [[f1=0, f2=0, f3=0, f4=0, g>=0, h>=0]];
  ord := [z,y,x,u,v]:
  R := PolynomialRing(ord):
  lsas := [[z^2 + x - y = 0, -u^2 + v^2 + z^2 - 1 = 0, z^2 + x + y = 0, u^2 - v^2 + z^2 - 1
    = 0, 0 ≤ x^2 - 1, 0 ≤ z]]

```

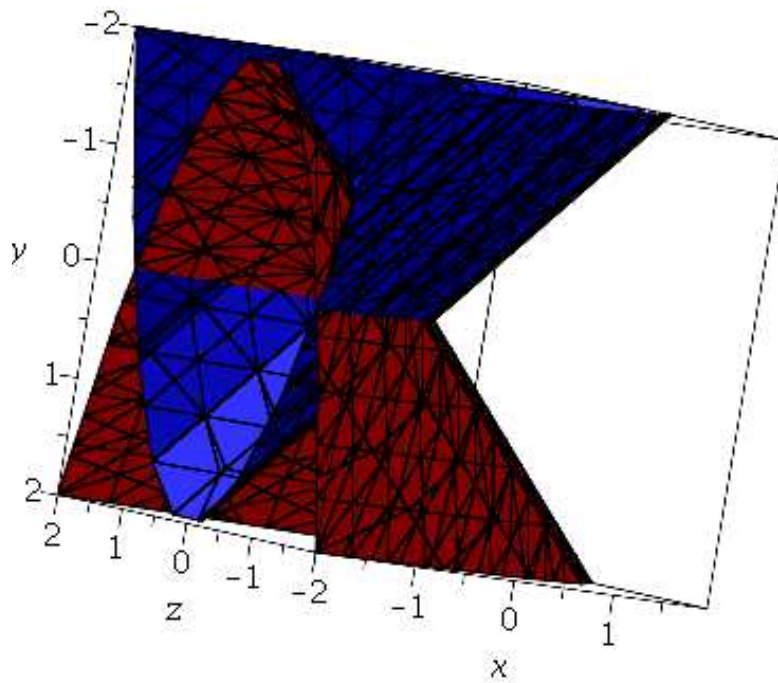
(1.1)

▼ Solution by hand

What is the solution?

Consider f_1 and f_3 on their own first

```
> implicitplot3d([f1,f3], x=-2..2, y=-2..2, z=-2..2, color=[red,blue]);
```

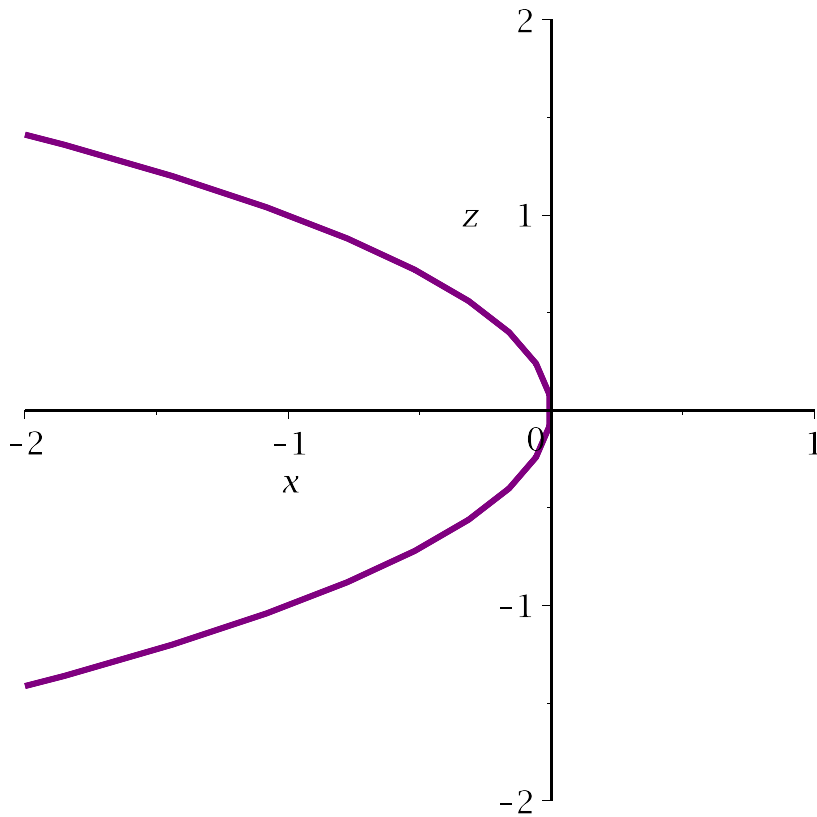


```
> resultant(f1, f3, z);
```

$$4y^2$$

(1.1.1)

```
> subs(y=0,[f1=0,f3=0]);  
plots:-implicitplot(% , x=-2..1, z=-2..2, color=["Purple"],  
thickness=3, view=[-2..1, -2..2]);  
[z2+x=0, z2+x=0]
```

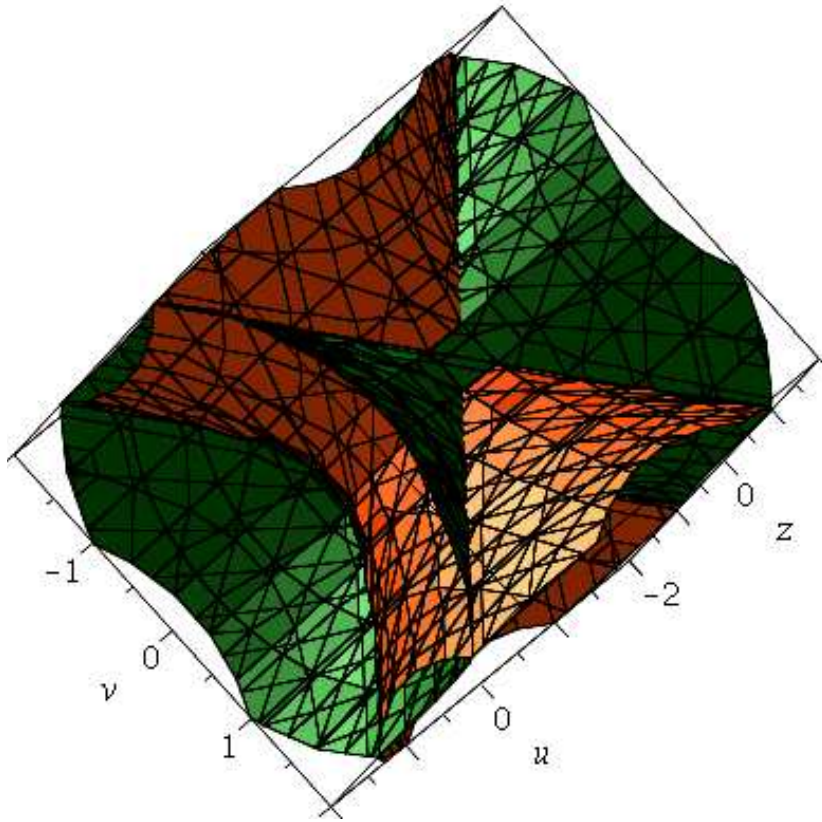


```
> subs(y=0, f1);  
subs(y=0, f3);
```

$$z^2 + x$$
$$z^2 + x$$

(1.1.2)

```
> implicitplot3d([f2,f4], u=-2..2, v=-2..2, z=-2..2, color=
["DarkGreen","OrangeRed"]);
```



```
> resultant(f2,f4,z); solve(%);
```

$$(2u^2 - 2v^2)^2$$

$$\{u = v, v = v\}, \{u = -v, v = v\} \quad (1.1.3)$$

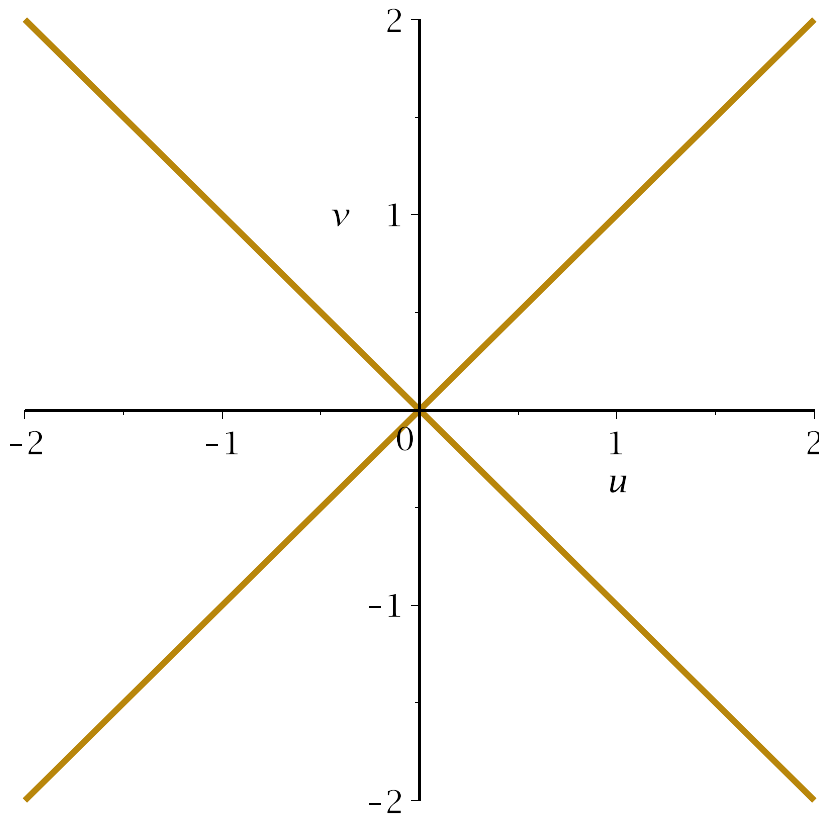
```
> algsubs(u^2=v^2, f2);
algsubs(u^2=v^2, f4);
```

$$z^2 - 1$$

$$z^2 - 1 \quad (1.1.4)$$

```
> subs(z=1, [f2,f4]);
plots:-implicitplot(% , u=-2..2, v=-2..2, color=
["DarkGoldenrod"], thickness=3, numpoints=400, view=[-2..2,
-2..2]);
#subs(z=-1, [f2,f4]);
#plots:-implicitplot(% , u=-2..2, v=-2..2, color=["Brown"],
thickness=3, numpoints=400, view=[-2..2, -2..2]);
```

$$[-u^2 + v^2, u^2 - v^2]$$



So we need $y=0$ and $u^2=v^2$. To satisfy the ECs together we thus need

```
> algssubs(u^2=v^2, subs(y=0, {f1,f2,f3,f4})); solve(%);
```

$$\{z^2 - 1, z^2 + x\}$$

$$\{x = -1, z = 1\}, \{x = -1, z = -1\} \quad (1.1.5)$$

$z = +/- 1$ and $x = -1$.

```
> algssubs(u^2=v^2, subs(x=-1,y=0, [f1,f2,f3,f4] )): convert(%,  
set);
```

$$\{z^2 - 1\} \quad (1.1.6)$$

But z must be positive from h and so only $z=+1$ allowed. The other non-EC, g , is satisfied by the x coordinate.

Two solution sets:

```
> Solution := { [x=-1, y=0, z=1, u=v], [x=-1, y=0, z=1, u=-v] };
```

$$\text{Solution} := \{[x = -1, y = 0, z = 1, u = v], [x = -1, y = 0, z = 1, u = -v]\} \quad (1.1.7)$$

What ECs are there?

We work systematically. In all 5 variables we have

> **f1;f2;f2;f3;**

$$\begin{aligned} & z^2 + x - y \\ & -u^2 + v^2 + z^2 - 1 \\ & -u^2 + v^2 + z^2 - 1 \\ & z^2 + x + y \end{aligned} \tag{1.2.1}$$

In 4 variables we have

> **[resultant(f1, f2, z),
resultant(f1, f3, z),
resultant(f1, f4, z),
resultant(f2, f3, z),
resultant(f2, f4, z),
resultant(f3, f4, z)];**

**L2EC:=convert(ProjectionCAD:-PCAD_SFBasis(select(X->has(X,
y), %) ,x), list);**

**L4EC:=convert(ProjectionCAD:-PCAD_SFBasis(remove(X->has(X,
y), %%), v), list);**

$$\begin{aligned} & [(-u^2 + v^2 - x + y - 1)^2, 4y^2, (u^2 - v^2 - x + y - 1)^2, (u^2 - v^2 + x + y + 1)^2, \\ & (2u^2 - 2v^2)^2, (u^2 - v^2 - x - y - 1)^2] \end{aligned}$$

$$\begin{aligned} L2EC := & [4y^2, -u^2 + v^2 + x - y + 1, -u^2 + v^2 + x + y + 1, u^2 - v^2 + x - y + 1, \\ & u^2 - v^2 + x + y + 1] \end{aligned}$$

$$L4EC := [-u^2 + v^2] \tag{1.2.2}$$

> **nops(L2EC);**

$$5 \tag{1.2.3}$$

> **[
resultant(L2EC[1], L2EC[2], y),
resultant(L2EC[1], L2EC[3], y),
resultant(L2EC[1], L2EC[4], y),
resultant(L2EC[1], L2EC[5], y),
resultant(L2EC[2], L2EC[3], y),
resultant(L2EC[2], L2EC[4], y),
resultant(L2EC[2], L2EC[5], y),
resultant(L2EC[3], L2EC[4], y),
resultant(L2EC[3], L2EC[5], y),
resultant(L2EC[4], L2EC[5], y)
];**

**L3EC := convert(ProjectionCAD:-PCAD_SFBasis(select(X->has
(X,x), %) ,x), list);**

**convert(ProjectionCAD:-PCAD_SFBasis(remove(X->has(X,x), %)
,v), list);**

$$[4(-u^2 + v^2 + x + 1)^2, 4(-u^2 + v^2 + x + 1)^2, 4(u^2 - v^2 + x + 1)^2, 4(u^2 - v^2$$

$$\begin{aligned}
& + x + 1)^2, 2u^2 - 2v^2 - 2x - 2, -2u^2 + 2v^2, -2x - 2, 2x + 2, 2u^2 \\
& - 2v^2, -2u^2 + 2v^2 - 2x - 2] \\
& L3EC := [x + 1, -u^2 + v^2 + x + 1, u^2 - v^2 + x + 1] \\
& \quad \quad \quad [] \tag{1.2.4}
\end{aligned}$$

$$\begin{aligned}
> \text{nops}(L3EC); \\
& \quad \quad \quad 3 \tag{1.2.5}
\end{aligned}$$

$$\begin{aligned}
> [\\
& \text{resultant}(L3EC[1], L3EC[2], x), \\
& \text{resultant}(L3EC[1], L3EC[3], x), \\
& \text{resultant}(L3EC[2], L3EC[3], x) \\
&]; \\
& L4EC := \text{convert}(\text{ProjectionCAD}:-\text{PCAD_SFBasis}(\text{select}(X \rightarrow \text{has}(X, \\
& u), \%), u), \text{list}); \\
& \text{convert}(\text{ProjectionCAD}:-\text{PCAD_SFBasis}(\text{remove}(X \rightarrow \text{has}(X, u), \% \\
& , v), \text{list}); \\
& \quad \quad \quad [-u^2 + v^2, u^2 - v^2, 2u^2 - 2v^2] \\
& \quad \quad \quad L4EC := [u^2 - v^2] \\
& \quad \quad \quad [] \tag{1.2.6}
\end{aligned}$$

$$\begin{aligned}
> L2EC; \\
& L3EC; \\
& L4EC; \\
& [4y^2, -u^2 + v^2 + x - y + 1, -u^2 + v^2 + x + y + 1, u^2 - v^2 + x - y + 1, u^2 - v^2 \\
& \quad + x + y + 1] \\
& \quad \quad \quad [x + 1, -u^2 + v^2 + x + 1, u^2 - v^2 + x + 1] \\
& \quad \quad \quad [u^2 - v^2] \tag{1.2.7}
\end{aligned}$$

$$\begin{aligned}
> L1EC := [f1, f2, f3, f4]; \\
& L2EC := [4*y^2, -u^2+v^2+x-y+1, -u^2+v^2+x+y+1, u^2-v^2+x-y+1, \\
& u^2-v^2+x+y+1]; \\
& L3EC := [x+1, -u^2+v^2+x+1, u^2-v^2+x+1]; \\
& L4EC := [u^2-v^2]; \\
& \quad L1EC := [z^2 + x - y, -u^2 + v^2 + z^2 - 1, z^2 + x + y, u^2 - v^2 + z^2 - 1] \\
& L2EC := [4y^2, -u^2 + v^2 + x - y + 1, -u^2 + v^2 + x + y + 1, u^2 - v^2 + x - y + 1, u^2 \\
& \quad - v^2 + x + y + 1] \\
& \quad L3EC := [x + 1, -u^2 + v^2 + x + 1, u^2 - v^2 + x + 1] \\
& \quad \quad L4EC := [u^2 - v^2] \tag{1.2}
\end{aligned}$$

Solutions using new ideas as described in paper

```
> resultant(f1, f2, z);
r1:=-u^2+v^2-x+y-1;
      (-u^2+v^2-x+y-1)^2
      r1:=-u^2+v^2-x+y-1
```

(1.3.1)

```
> A5:={f1, f2, f3, f4, g, h}: A5:=ProjectionCAD:-PCAD_SFBasis(A5, z)
;
E5:={f1};
A5 := {z, x^2-1, z^2+x-y, z^2+x+y, -u^2+v^2+z^2-1, u^2-v^2+z^2-1}
      E5 := {z^2+x-y}
```

(1.3.2)

No need for extra discriminants as first projection

```
> A4 := [ op(ProjectionCAD:-ECCADProjOp( E5, A5, ord)) ]:
A4 := ProjectionCAD:-PCAD_SFBasis(%, y);
E4 := [r1];
      A4 := {y, (x^2-1)^2, -x+y, -u^2+v^2-x+y-1, u^2-v^2-x+y-1}
      E4 := [-u^2+v^2-x+y-1]
```

(1.3.3)

This time need to consider extra discrim

```
> A3 := { op(ProjectionCAD:-ECCADProjOp( convert(E4, set),
      convert(A4, set), [y, x, u, v])) );
      convert(map(X->discrim(X, y), expand(A4)), set);
      A3 := {(x^2-1)^2, 2 u^2-2 v^2, u^2-v^2+1, u^2-v^2+x+1}
      {0, 1}
```

(1.3.4)

All evaluate to constants

```
> resultant( resultant(f1, f2, z), resultant(f1, f3, z), y);
r2:=u^2-v^2+x+1;
      16 (u^2-v^2+x+1)^4
      r2:=u^2-v^2+x+1
```

(1.3.5)

```
> A3 := ProjectionCAD:-PCAD_SFBasis(A3, x);
E3:=[r2];
      A3 := {x^2-1, 2 u^2-2 v^2, u^2-v^2+1, u^2-v^2+x+1}
      E3 := [u^2-v^2+x+1]
```

(1.3.6)

consider extra discriminants

```
> A2 := { op(ProjectionCAD:-ECCADProjOp( convert(E3, set),
      convert(A3, set), [x, u, v])) );
      convert(map(X->discrim(X, x), A3), set);
      A2 := {2 u^2-2 v^2, u^2-v^2+1, u^4-2 u^2 v^2+v^4+2 u^2-2 v^2}
      {0, 1, 4}
```

(1.3.7)

All evaluate to constants.


```

> resultant( RR, resultant(f1,f4,z), y);
r3:=u^2-v^2;

$$\frac{(2u^2 - 2v^2)^2}{r3 := u^2 - v^2} \tag{1.3.8}$$


```

```

> A2 := ProjectionCAD:-PCAD_SFBasis(A2, u);
E2:=[u^2-v^2]; factor(%);

$$A2 := \{u^2 - v^2, u^2 - v^2 + 1, u^4 - 2u^2v^2 + v^4 + 2u^2 - 2v^2\}$$


$$E2 := [u^2 - v^2]$$


$$[(u - v) (u + v)] \tag{1.3.9}$$


```

No need for discrim in final projection.

```

> A1 := { op(ProjectionCAD:-ECCADProjOp( convert(E2,set),
convert(A2,set), [u,v])) } ; #convert(map(X->discrim(X,x),
Ad),set);

$$A1 := \{v^2\} \tag{1.3.10}$$


```

Only one polynomial.

```

> cadL1:=ProjectionCAD:-CADFull( A1, [v], method=McCallum,
output=listwithrep, finalCAD=0I): nops(%);

$$3 \tag{1.3.11}$$


```

```

> E2; factor(%);

$$[u^2 - v^2]$$


$$[(u - v) (u + v)] \tag{1.3.12}$$


```

NB nothing in E2 nullified at v=0.

There was no E1

```

> out := []:
for i from 1 to nops(cadL1) do
cell := cadL1[i]:
stk := ProjectionCAD:-CADGenerateStack( cadL1[i], E2, [u,
v], output=listwithrep):
out := [op(out), op(stk)]:
od:
nops(out);
cadL2:=out:

$$13 \tag{1.3.13}$$


```

Clearly E3 cannot be nullified by any (u,v) value independent of x

```

> E3;

$$[u^2 - v^2 + x + 1] \tag{1.3.14}$$


```

```

> out := []:
  for i from 1 to nops(cadL2) do
    cell := cadL2[i]:
    if cell[1][-1]::even then
      stk := ProjectionCAD:-CADGenerateStack( cell, E3, [x,u,
v], output=listwithrep):
      out := [op(out), op(stk)]:
    else
      stk := ProjectionCAD:-CADGenerateStack( cell, [1], [x,u,
v], output=listwithrep):
      out := [op(out), op(stk)]:
    fi:
  od:
  nops(out);
  cadL3:=out:

```

23 (1.3.15)

```

> out := []:
  for i from 1 to nops(cadL3) do
    cell := cadL3[i]:
    if cell[1][-2]::even then
      stk := ProjectionCAD:-CADGenerateStack( cell, E4, [y,x,
u,v], output=listwithrep):
      out := [op(out), op(stk)]:
    else
      stk := ProjectionCAD:-CADGenerateStack( cell, [1], [y,x,
u,v], output=listwithrep):
      out := [op(out), op(stk)]:
    fi:
  od:
  nops(out);
  cadL4:=out:

```

53 (1.3.16)

```

> out := []:
  for i from 1 to nops(cadL4) do
    cell := cadL4[i]:
    if cell[1][-1]::even and cell[1][-3]::even then
      stk := ProjectionCAD:-CADGenerateStack( cell, E5, [z,y,
x,u,v], output=listwithrep):
      out := [op(out), op(stk)]:
    else
      stk := ProjectionCAD:-CADGenerateStack( cell, [1], [z,y,
x,u,v], output=listwithrep):
      out := [op(out), op(stk)]:
    fi:
  od:
  nops(out);
  cadL5:=out:

```

113 (1.3.17)

```

> cadL5[13][2];
cadL5[35][2];
cadL5[58][2];
cadL5[81][2];
cadL5[103][2];

```

$$\begin{aligned}
& [v < 0, u = v, x = -1, y = 0, z = 1] \\
& [v < 0, u = -v, x = -1, y = 0, z = 1] \\
& [v = 0, u = 0, x = -1, y = 0, z = 1] \\
& [0 < v, u = -v, x = -1, y = 0, z = 1] \\
& [0 < v, u = v, x = -1, y = 0, z = 1]
\end{aligned}$$

(1.3.18)

```

> Solution;

```

$$\{ [x = -1, y = 0, z = 1, u = v], [x = -1, y = 0, z = 1, u = -v] \}$$

(1.3.19)

```

[Solution in 5 cells.

```

[In the above we made choices about which EC to use.
[We observe what would of happened with different choices.

▼ Different choices

```
> RunTheTest:=proc(Choice)
  local E5,E4,E3,E2,A5,A4,A3,A2,A1,cadL1,cadL2,cadL3,cadL4,
  cadL5,out,stk,cell,set,st,et,i;

  E5:={L1EC[Choice[1]]};
  E4:={L2EC[Choice[2]]};
  E3:={L3EC[Choice[3]]};
  E2:={L4EC[Choice[4]]};
  print(E5,E4,E3,E2);

  st:=time():

  A5:={f1,f2,f3,f4,g,h};

  A4 := ProjectionCAD:-ECCADProjOp( E5, A5, [z,y,x,u,v]):
  A4 := remove(X->X::constant, A4):
  A4 := ProjectionCAD:-PCAD_SFBasis(%, y);

  A3 := { op(ProjectionCAD:-ECCADProjOp( convert(E4,set),
  convert(A4,set), [y,x,u,v])), op(map(X->discrim(X,y), expand
  (A4))))}:
  A3 := remove(X->X::constant, A3):
  A3 := ProjectionCAD:-PCAD_SFBasis(%, x);

  A2 := { op(ProjectionCAD:-ECCADProjOp( convert(E3,set),
  convert(A3,set), [x,u,v])), op(map(X->discrim(X,x), A3)) } :
  A2 := remove(X->X::constant, A2):
  A2 := ProjectionCAD:-PCAD_SFBasis(%, u);

  A1 := { op(ProjectionCAD:-ECCADProjOp( convert(E2,set),
  convert(A2,set), [u,v]))}:
  A1 := remove(X->X::constant, A1);

  cadL1:=ProjectionCAD:-CADFull( A1, [v], method=McCallum,
  output=listwithrep, finalCAD=0I):
  #print("R1:", nops(%));

  out := []:
  for i from 1 to nops(cadL1) do
    cell := cadL1[i]:
    stk := ProjectionCAD:-CADGenerateStack( cadL1[i], E2, [u,
  v], output=listwithrep):
    out := [op(out), op(stk)]:
  od:
  cadL2:=out:
  #print("R2:", nops(%));
```

```

out := []:
for i from 1 to nops(cadL2) do
  cell := cadL2[i]:
  if cell[1][-1]::even then
    stk := ProjectionCAD:-CADGenerateStack( cell, E3, [x,u,
v], output=listwithrep):
    out := [op(out), op(stk)]:
  else
    stk := ProjectionCAD:-CADGenerateStack( cell, [1], [x,u,
v], output=listwithrep):
    out := [op(out), op(stk)]:
  fi:
od:
cadL3:=out:
#print("R3:", nops(%));

```

```

out := []:
for i from 1 to nops(cadL3) do
  cell := cadL3[i]:
  if cell[1][-2]::even then
    stk := ProjectionCAD:-CADGenerateStack( cell, E4, [y,x,
u,v], output=listwithrep):
    out := [op(out), op(stk)]:
  else
    stk := ProjectionCAD:-CADGenerateStack( cell, [1], [y,x,
u,v], output=listwithrep):
    out := [op(out), op(stk)]:
  fi:
od:
cadL4:=out:
#print("R4:", nops(%));

```

```

out := []:
for i from 1 to nops(cadL4) do
  cell := cadL4[i]:
  if cell[1][-1]::even and cell[1][-3]::even then
    stk := ProjectionCAD:-CADGenerateStack( cell, E5, [z,y,
x,u,v], output=listwithrep):
    out := [op(out), op(stk)]:
  else
    stk := ProjectionCAD:-CADGenerateStack( cell, [1], [z,y,
x,u,v], output=listwithrep):
    out := [op(out), op(stk)]:
  fi:
od:
cadL5:=out:
#print("R5:", nops(%));

```

```

print("Cells:", nops(cadL5));
et:=time()-st;
print("Time:", et):

return( nops(cadL5) );
end proc:
> nops(L1EC), nops(L2EC), nops(L3EC), nops(L4EC);
4, 5, 3, 1 (1.4.1)

> Choices := [
[1,1,1,1], [1,1,2,1], [1,1,3,1],
[1,2,1,1], [1,2,2,1], [1,2,3,1],
[1,3,1,1], [1,3,2,1], [1,3,3,1],
[1,4,1,1], [1,4,2,1], [1,4,3,1],
[1,5,1,1], [1,5,2,1], [1,5,3,1],

[2,1,1,1], [2,1,2,1], [2,1,3,1],
[2,2,1,1], [2,2,2,1], [2,2,3,1],
[2,3,1,1], [2,3,2,1], [2,3,3,1],
[2,4,1,1], [2,4,2,1], [2,4,3,1],
[2,5,1,1], [2,5,2,1], [2,5,3,1],

[3,1,1,1], [3,1,2,1], [3,1,3,1],
[3,2,1,1], [3,2,2,1], [3,2,3,1],
[3,3,1,1], [3,3,2,1], [3,3,3,1],
[3,4,1,1], [3,4,2,1], [3,4,3,1],
[3,5,1,1], [3,5,2,1], [3,5,3,1],

[4,1,1,1], [4,1,2,1], [4,1,3,1],
[4,2,1,1], [4,2,2,1], [4,2,3,1],
[4,3,1,1], [4,3,2,1], [4,3,3,1],
[4,4,1,1], [4,4,2,1], [4,4,3,1],
[4,5,1,1], [4,5,2,1], [4,5,3,1]
];
nops(Choices);
Choices := [[1, 1, 1, 1], [1, 1, 2, 1], [1, 1, 3, 1], [1, 2, 1, 1], [1, 2, 2, 1], [1,
2, 3, 1], [1, 3, 1, 1], [1, 3, 2, 1], [1, 3, 3, 1], [1, 4, 1, 1], [1, 4, 2, 1], [1,
4, 3, 1], [1, 5, 1, 1], [1, 5, 2, 1], [1, 5, 3, 1], [2, 1, 1, 1], [2, 1, 2, 1], [2,
1, 3, 1], [2, 2, 1, 1], [2, 2, 2, 1], [2, 2, 3, 1], [2, 3, 1, 1], [2, 3, 2, 1], [2,
3, 3, 1], [2, 4, 1, 1], [2, 4, 2, 1], [2, 4, 3, 1], [2, 5, 1, 1], [2, 5, 2, 1], [2,
5, 3, 1], [3, 1, 1, 1], [3, 1, 2, 1], [3, 1, 3, 1], [3, 2, 1, 1], [3, 2, 2, 1], [3,
2, 3, 1], [3, 3, 1, 1], [3, 3, 2, 1], [3, 3, 3, 1], [3, 4, 1, 1], [3, 4, 2, 1], [3,
4, 3, 1], [3, 5, 1, 1], [3, 5, 2, 1], [3, 5, 3, 1], [4, 1, 1, 1], [4, 1, 2, 1], [4,
1, 3, 1], [4, 2, 1, 1], [4, 2, 2, 1], [4, 2, 3, 1], [4, 3, 1, 1], [4, 3, 2, 1], [4,
3, 3, 1], [4, 4, 1, 1], [4, 4, 2, 1], [4, 4, 3, 1], [4, 5, 1, 1], [4, 5, 2, 1], [4,
5, 3, 1]]

```

```

> Results:=[]:
  for ord in Choices do
    print("-----");
    print(ord);
    N := RunTheTest(ord);
    Results:=[op(Results), N]:
  od:
      "-----"
      [1, 1, 1, 1]
      {z2 + x - y}, {4 y2}, {x + 1}, {u2 - v2}
      "Cells:", 103
      "Time:", 0.360
      "-----"
      [1, 1, 2, 1]
      {z2 + x - y}, {4 y2}, {-u2 + v2 + x + 1}, {u2 - v2}
      "Cells:", 103
      "Time:", 0.346
      "-----"
      [1, 1, 3, 1]
      {z2 + x - y}, {4 y2}, {u2 - v2 + x + 1}, {u2 - v2}
      "Cells:", 103
      "Time:", 0.424
      "-----"
      [1, 2, 1, 1]
      {z2 + x - y}, {-u2 + v2 + x - y + 1}, {x + 1}, {u2 - v2}
      "Cells:", 113
      "Time:", 0.408
      "-----"
      [1, 2, 2, 1]
      {z2 + x - y}, {-u2 + v2 + x - y + 1}, {-u2 + v2 + x + 1}, {u2 - v2}
      "Cells:", 113
      "Time:", 0.498
      "-----"
      [1, 2, 3, 1]
      {z2 + x - y}, {-u2 + v2 + x - y + 1}, {u2 - v2 + x + 1}, {u2 - v2}
      "Cells:", 113
      "Time:", 0.410
      "-----"

```

[1, 3, 1, 1]
{z² + x - y}, {-u² + v² + x + y + 1}, {x + 1}, {u² - v²}
"Cells:", 93
"Time:", 0.470

"-----"

[1, 3, 2, 1]
{z² + x - y}, {-u² + v² + x + y + 1}, {-u² + v² + x + 1}, {u² - v²}
"Cells:", 93
"Time:", 0.352

"-----"

[1, 3, 3, 1]
{z² + x - y}, {-u² + v² + x + y + 1}, {u² - v² + x + 1}, {u² - v²}
"Cells:", 93
"Time:", 0.353

"-----"

[1, 4, 1, 1]
{z² + x - y}, {u² - v² + x - y + 1}, {x + 1}, {u² - v²}
"Cells:", 113
"Time:", 0.499

"-----"

[1, 4, 2, 1]
{z² + x - y}, {u² - v² + x - y + 1}, {-u² + v² + x + 1}, {u² - v²}
"Cells:", 113
"Time:", 0.414

"-----"

[1, 4, 3, 1]
{z² + x - y}, {u² - v² + x - y + 1}, {u² - v² + x + 1}, {u² - v²}
"Cells:", 113
"Time:", 0.503

"-----"

[1, 5, 1, 1]
{z² + x - y}, {u² - v² + x + y + 1}, {x + 1}, {u² - v²}
"Cells:", 93
"Time:", 0.354

"-----"

[1, 5, 2, 1]
{z² + x - y}, {u² - v² + x + y + 1}, {-u² + v² + x + 1}, {u² - v²}

"Cells:", 93

"Time:", 0.441

"-----"

[1, 5, 3, 1]

$\{z^2 + x - y\}$, $\{u^2 - v^2 + x + y + 1\}$, $\{u^2 - v^2 + x + 1\}$, $\{u^2 - v^2\}$

"Cells:", 93

"Time:", 0.356

"-----"

[2, 1, 1, 1]

$\{-u^2 + v^2 + z^2 - 1\}$, $\{4y^2\}$, $\{x + 1\}$, $\{u^2 - v^2\}$

"Cells:", 113

"Time:", 0.483

"-----"

[2, 1, 2, 1]

$\{-u^2 + v^2 + z^2 - 1\}$, $\{4y^2\}$, $\{-u^2 + v^2 + x + 1\}$, $\{u^2 - v^2\}$

"Cells:", 113

"Time:", 0.375

"-----"

[2, 1, 3, 1]

$\{-u^2 + v^2 + z^2 - 1\}$, $\{4y^2\}$, $\{u^2 - v^2 + x + 1\}$, $\{u^2 - v^2\}$

"Cells:", 113

"Time:", 0.467

"-----"

[2, 2, 1, 1]

$\{-u^2 + v^2 + z^2 - 1\}$, $\{-u^2 + v^2 + x - y + 1\}$, $\{x + 1\}$, $\{u^2 - v^2\}$

"Cells:", 113

"Time:", 0.406

"-----"

[2, 2, 2, 1]

$\{-u^2 + v^2 + z^2 - 1\}$, $\{-u^2 + v^2 + x - y + 1\}$, $\{-u^2 + v^2 + x + 1\}$, $\{u^2 - v^2\}$

"Cells:", 113

"Time:", 0.501

"-----"

[2, 2, 3, 1]

$\{-u^2 + v^2 + z^2 - 1\}$, $\{-u^2 + v^2 + x - y + 1\}$, $\{u^2 - v^2 + x + 1\}$, $\{u^2 - v^2\}$

"Cells:", 113

"Time:", 0.408

"-----"

[2, 3, 1, 1]

$\{-u^2 + v^2 + z^2 - 1\}, \{-u^2 + v^2 + x + y + 1\}, \{x + 1\}, \{u^2 - v^2\}$

"Cells:", 113

"Time:", 0.420

"-----"

[2, 3, 2, 1]

$\{-u^2 + v^2 + z^2 - 1\}, \{-u^2 + v^2 + x + y + 1\}, \{-u^2 + v^2 + x + 1\}, \{u^2 - v^2\}$

"Cells:", 113

"Time:", 0.494

"-----"

[2, 3, 3, 1]

$\{-u^2 + v^2 + z^2 - 1\}, \{-u^2 + v^2 + x + y + 1\}, \{u^2 - v^2 + x + 1\}, \{u^2 - v^2\}$

"Cells:", 113

"Time:", 0.408

"-----"

[2, 4, 1, 1]

$\{-u^2 + v^2 + z^2 - 1\}, \{u^2 - v^2 + x - y + 1\}, \{x + 1\}, \{u^2 - v^2\}$

"Cells:", 113

"Time:", 0.505

"-----"

[2, 4, 2, 1]

$\{-u^2 + v^2 + z^2 - 1\}, \{u^2 - v^2 + x - y + 1\}, \{-u^2 + v^2 + x + 1\}, \{u^2 - v^2\}$

"Cells:", 113

"Time:", 0.412

"-----"

[2, 4, 3, 1]

$\{-u^2 + v^2 + z^2 - 1\}, \{u^2 - v^2 + x - y + 1\}, \{u^2 - v^2 + x + 1\}, \{u^2 - v^2\}$

"Cells:", 113

"Time:", 0.505

"-----"

[2, 5, 1, 1]

$\{-u^2 + v^2 + z^2 - 1\}, \{u^2 - v^2 + x + y + 1\}, \{x + 1\}, \{u^2 - v^2\}$

"Cells:", 113

"Time:", 0.406

"-----"

[2, 5, 2, 1]

```

{-u2 + v2 + z2 - 1}, {u2 - v2 + x + y + 1}, {-u2 + v2 + x + 1}, {u2 - v2}
"Cells:", 113
"Time:", 0.492
"-----"
[2, 5, 3, 1]
{-u2 + v2 + z2 - 1}, {u2 - v2 + x + y + 1}, {u2 - v2 + x + 1}, {u2 - v2}
"Cells:", 113
"Time:", 0.406
"-----"
[3, 1, 1, 1]
{z2 + x + y}, {4 y2}, {x + 1}, {u2 - v2}
"Cells:", 103
"Time:", 0.429
"-----"
[3, 1, 2, 1]
{z2 + x + y}, {4 y2}, {-u2 + v2 + x + 1}, {u2 - v2}
"Cells:", 103
"Time:", 0.337
"-----"
[3, 1, 3, 1]
{z2 + x + y}, {4 y2}, {u2 - v2 + x + 1}, {u2 - v2}
"Cells:", 103
"Time:", 0.423
"-----"
[3, 2, 1, 1]
{z2 + x + y}, {-u2 + v2 + x - y + 1}, {x + 1}, {u2 - v2}
"Cells:", 93
"Time:", 0.363
"-----"
[3, 2, 2, 1]
{z2 + x + y}, {-u2 + v2 + x - y + 1}, {-u2 + v2 + x + 1}, {u2 - v2}
"Cells:", 93
"Time:", 0.356
"-----"
[3, 2, 3, 1]
{z2 + x + y}, {-u2 + v2 + x - y + 1}, {u2 - v2 + x + 1}, {u2 - v2}
"Cells:", 93

```

```

"Time:", 0.451
"-----"
[3, 3, 1, 1]
{z2 + x + y}, {-u2 + v2 + x + y + 1}, {x + 1}, {u2 - v2}
"Cells:", 113
"Time:", 0.426
"-----"
[3, 3, 2, 1]
{z2 + x + y}, {-u2 + v2 + x + y + 1}, {-u2 + v2 + x + 1}, {u2 - v2}
"Cells:", 113
"Time:", 0.520
"-----"
[3, 3, 3, 1]
{z2 + x + y}, {-u2 + v2 + x + y + 1}, {u2 - v2 + x + 1}, {u2 - v2}
"Cells:", 113
"Time:", 0.410
"-----"
[3, 4, 1, 1]
{z2 + x + y}, {u2 - v2 + x - y + 1}, {x + 1}, {u2 - v2}
"Cells:", 93
"Time:", 0.449
"-----"
[3, 4, 2, 1]
{z2 + x + y}, {u2 - v2 + x - y + 1}, {-u2 + v2 + x + 1}, {u2 - v2}
"Cells:", 93
"Time:", 0.355
"-----"
[3, 4, 3, 1]
{z2 + x + y}, {u2 - v2 + x - y + 1}, {u2 - v2 + x + 1}, {u2 - v2}
"Cells:", 93
"Time:", 0.366
"-----"
[3, 5, 1, 1]
{z2 + x + y}, {u2 - v2 + x + y + 1}, {x + 1}, {u2 - v2}
"Cells:", 113
"Time:", 0.500
"-----"

```

[3, 5, 2, 1]
{ $z^2 + x + y$ }, { $u^2 - v^2 + x + y + 1$ }, { $-u^2 + v^2 + x + 1$ }, { $u^2 - v^2$ }
"Cells:", 113
"Time:", 0.412
"-----"

[3, 5, 3, 1]
{ $z^2 + x + y$ }, { $u^2 - v^2 + x + y + 1$ }, { $u^2 - v^2 + x + 1$ }, { $u^2 - v^2$ }
"Cells:", 113
"Time:", 0.516
"-----"

[4, 1, 1, 1]
{ $u^2 - v^2 + z^2 - 1$ }, { $4y^2$ }, { $x + 1$ }, { $u^2 - v^2$ }
"Cells:", 113
"Time:", 0.383
"-----"

[4, 1, 2, 1]
{ $u^2 - v^2 + z^2 - 1$ }, { $4y^2$ }, { $-u^2 + v^2 + x + 1$ }, { $u^2 - v^2$ }
"Cells:", 113
"Time:", 0.481
"-----"

[4, 1, 3, 1]
{ $u^2 - v^2 + z^2 - 1$ }, { $4y^2$ }, { $u^2 - v^2 + x + 1$ }, { $u^2 - v^2$ }
"Cells:", 113
"Time:", 0.376
"-----"

[4, 2, 1, 1]
{ $u^2 - v^2 + z^2 - 1$ }, { $-u^2 + v^2 + x - y + 1$ }, { $x + 1$ }, { $u^2 - v^2$ }
"Cells:", 113
"Time:", 0.512
"-----"

[4, 2, 2, 1]
{ $u^2 - v^2 + z^2 - 1$ }, { $-u^2 + v^2 + x - y + 1$ }, { $-u^2 + v^2 + x + 1$ }, { $u^2 - v^2$ }
"Cells:", 113
"Time:", 0.413
"-----"

[4, 2, 3, 1]
{ $u^2 - v^2 + z^2 - 1$ }, { $-u^2 + v^2 + x - y + 1$ }, { $u^2 - v^2 + x + 1$ }, { $u^2 - v^2$ }

"Cells:", 113

"Time:", 0.517

"-----"

[4, 3, 1, 1]

$\{u^2 - v^2 + z^2 - 1\}$, $\{-u^2 + v^2 + x + y + 1\}$, $\{x + 1\}$, $\{u^2 - v^2\}$

"Cells:", 113

"Time:", 0.430

"-----"

[4, 3, 2, 1]

$\{u^2 - v^2 + z^2 - 1\}$, $\{-u^2 + v^2 + x + y + 1\}$, $\{-u^2 + v^2 + x + 1\}$, $\{u^2 - v^2\}$

"Cells:", 113

"Time:", 0.506

"-----"

[4, 3, 3, 1]

$\{u^2 - v^2 + z^2 - 1\}$, $\{-u^2 + v^2 + x + y + 1\}$, $\{u^2 - v^2 + x + 1\}$, $\{u^2 - v^2\}$

"Cells:", 113

"Time:", 0.416

"-----"

[4, 4, 1, 1]

$\{u^2 - v^2 + z^2 - 1\}$, $\{u^2 - v^2 + x - y + 1\}$, $\{x + 1\}$, $\{u^2 - v^2\}$

"Cells:", 113

"Time:", 0.512

"-----"

[4, 4, 2, 1]

$\{u^2 - v^2 + z^2 - 1\}$, $\{u^2 - v^2 + x - y + 1\}$, $\{-u^2 + v^2 + x + 1\}$, $\{u^2 - v^2\}$

"Cells:", 113

"Time:", 0.423

"-----"

[4, 4, 3, 1]

$\{u^2 - v^2 + z^2 - 1\}$, $\{u^2 - v^2 + x - y + 1\}$, $\{u^2 - v^2 + x + 1\}$, $\{u^2 - v^2\}$

"Cells:", 113

"Time:", 0.512

"-----"

[4, 5, 1, 1]

$\{u^2 - v^2 + z^2 - 1\}$, $\{u^2 - v^2 + x + y + 1\}$, $\{x + 1\}$, $\{u^2 - v^2\}$

"Cells:", 113

"Time:", 0.404

```

"-----"
      [4, 5, 2, 1]
{u2 - v2 + z2 - 1}, {u2 - v2 + x + y + 1}, {-u2 + v2 + x + 1}, {u2 - v2}
      "Cells:", 113
      "Time:", 0.525
"-----"
      [4, 5, 3, 1]
{u2 - v2 + z2 - 1}, {u2 - v2 + x + y + 1}, {u2 - v2 + x + 1}, {u2 - v2}
      "Cells:", 113
      "Time:", 0.414

```

(1.4.3)

> **Results;**

```

[103, 103, 103, 113, 113, 113, 93, 93, 93, 113, 113, 113, 93, 93, 93, 113,
 113, 113, 113, 113, 113, 113, 113, 113, 113, 113, 113, 113, 113,
 103, 103, 103, 93, 93, 93, 113, 113, 113, 93, 93, 93, 113, 113, 113,
 113, 113, 113, 113, 113, 113, 113, 113, 113, 113, 113, 113, 113]

```

(1.4.4)

> **min(Results);**

93

(1.4.5)

```

> for i from 1 to 60 do
if Results[i]=93 then print(i, Choices[i]); fi:
od:

```

```

      7, [1, 3, 1, 1]
      8, [1, 3, 2, 1]
      9, [1, 3, 3, 1]
     13, [1, 5, 1, 1]
     14, [1, 5, 2, 1]
     15, [1, 5, 3, 1]
     34, [3, 2, 1, 1]
     35, [3, 2, 2, 1]
     36, [3, 2, 3, 1]
     40, [3, 4, 1, 1]
     41, [3, 4, 2, 1]
     42, [3, 4, 3, 1]

```

(1.4.6)